

# Statistical convergence rates for transport- and ODE-based models

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WIAS Mathematical Statistics Seminar

HUMBOLDT-  
UNIVERSITÄT  
ZU BERLIN



November 8, 2023

An important goal in statistics (and machine learning) is to learn complicated probability distributions  $\pi$ .

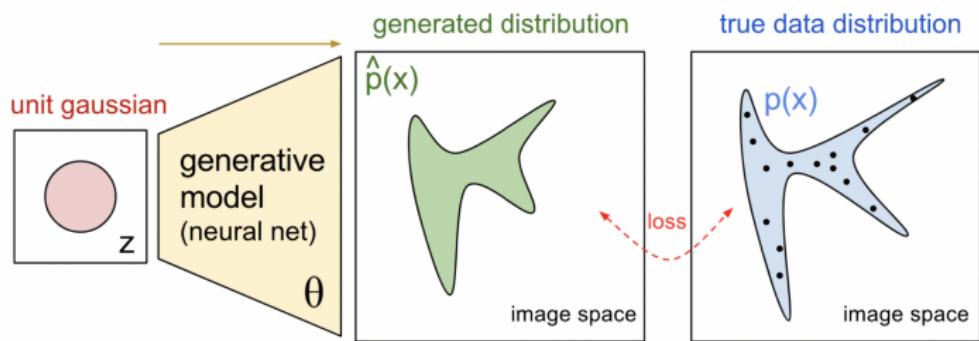
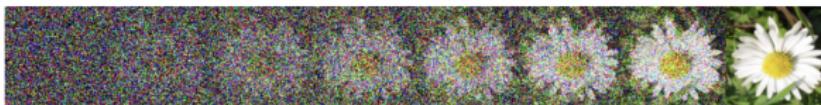
- ▶ **Generate samples**  $Z$  with approximate law  $\mathcal{L}(Z) \approx \pi$ .
- ▶ **Estimate**  $\hat{\pi} \approx \pi$ .

Depending on the context, we have access either

- ▶ Data  $X_1, \dots, X_N$  (**Density estimation / generative modelling**).
- ▶ Evaluations of  $\pi(\cdot)$  up to normalization constant or  $\nabla \log \pi$  (**Bayesian computation / sampling**).

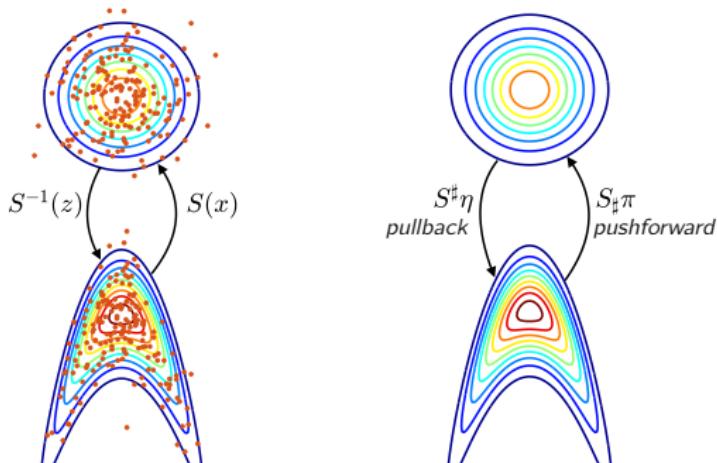
# Recent strategies for generative modelling

- ▶ Normalising flows: composition of bijective maps [Rezende & Mohamed 2015]
- ▶ Autoregressive flows: composition of triangular maps [Kingma et al. 2018]
- ▶ NeuralODE [Chen et al. 2018]
- ▶ Score-based diffusion models [Song et al. 2021]
- ▶ Stochastic interpolants [Albergo & Vanden-Eijnden 2022]



# Transport methods

- ▶ A **transport map  $S$**  induces a *deterministic coupling* between a target distribution  $\pi$  and a reference distribution  $\eta$ 
  - ▶ Choose  $\eta$  to be simple/tractable (standard normal, uniform)
  - ▶ Find an invertible  $S$  such that  $S_{\sharp}\pi = \eta$
  - ▶ Estimate the target density:  $\pi(\mathbf{x}) = S^{\sharp}\eta(\mathbf{x}) := \eta \circ S(\mathbf{x}) |\det \nabla S(\mathbf{x})|$
  - ▶ Generate cheap and independent samples:  $\mathbf{Z} \sim \eta \Leftrightarrow S^{-1}(\mathbf{Z}) \sim \pi$
  - ▶ Bayesian computation via transport [Marzouk et al. (2016)]



# Classes of transport maps

- ▶ There are many ways to couple  $\pi$  and  $\eta$ .
  - ▶ **Brenier maps:** Under mild assumptions on  $\pi, \eta$ , there exists a unique map  $S_{\pi,\eta}^{OT}$  (gradient of some convex function) such that  $(S_{\pi,\eta}^{OT})_\sharp \pi = \eta$  and

$$W^2(\eta, \pi) = \int \|x - S_{\pi,\eta}^{OT}(x)\|^2 d\pi(x),$$

i.e.  $(Id \times \nabla S_{\pi,\eta}^{OT})_\sharp \pi$  is an optimal coupling.

- ▶ **Knothe-Rosenblatt maps:** Triangular, partially monotone maps (equal to OT maps for  $d = 1$ )
- ▶ **ODE flow maps:** Evolving  $\pi$  (at  $t = 0$ ) to  $\eta$  (at  $t = 1$ ) through an ODE flow,

$$\frac{dX(t)}{dt} = f(X(t), t), \quad X(0) \sim \pi, \quad X(1) \sim \eta.$$

- ▶ Statistical performance of those methods?
- ▶ Can they achieve minimax rates?

## Existing theory work

- ▶ **Approximation** of transport maps in high dimension using sparse polynomials or ReLU networks [Zech & Marzouk (2021)]
- ▶ **Statistical consistency** for triangular maps in KL-distance [Irons et al. (2022)]
- ▶ **Estimation of OT maps:** Minimax rate in  $d$  dimensions:  
 $N^{-\frac{\alpha}{2\alpha-2+d}} \vee N^{-1}$ . [Hütter & Rigollet (2021, AOS)]
- ▶ **Computational OT** [Peyré & Cuturi (2019)]
- ▶ **Density estimation** for Wasserstein loss [Weed & Berthet (2019), Hütter and Rigollet (2021)]
- ▶ **Diffusion models** [Oko, Akiyama, Suzuki (2023)]

# Nonparametric density estimation via transport

- **Data.** We are given  $N$  i.i.d. observations on  $[0, 1]^d$ ,

$$X_1, \dots, X_N \sim P_0.$$

- **Goal.** Estimate unknown Lebesgue density  $p_0$  within some class  $\mathcal{P}$ .

## Likelihood objective

For some class  $\mathcal{S}$  of bijective maps  $[0, 1]^d \rightarrow [0, 1]^d$ , take

$$\begin{aligned}\hat{S} \in \arg \min_{S \in \mathcal{S}} -\frac{1}{N} \sum_{i=1}^N \log (\eta \circ S(X_i) \det \nabla S(X_i)) \\ \left( \approx \arg \min_{S \in \mathcal{S}} KL(p_0 || S^\# \eta) + \text{const.} \right)\end{aligned}$$

- How should one choose  $\mathcal{S}$ ?

## Monotone triangular transport maps

Let us now focus on **Knothe–Rosenblatt (KR) rearrangements** on unit cube  $[0, 1]^d$

$$S_{\pi, \eta}(x) \equiv S(x) = \begin{bmatrix} S_1(x_1) \\ S_2(x_1, x_2) \\ \vdots \\ S_d(x_1, x_2, \dots, x_d) \end{bmatrix}, \quad S^\# \eta = \pi.$$

- ▶ Exists and is unique under mild assumptions on  $\pi$  and  $\eta$  (given a variable ordering)
- ▶ Invertibility is guaranteed by one-dimensional monotonicity  $\partial_k S_k > 0$
- ▶  $\det \nabla S(\mathbf{x})$  simple to evaluate
- ▶ Components  $S_k$  characterize marginal conditionals of  $\pi$ :

$$\pi_{\mathbf{X}} = \pi_{\mathbf{X}_1} \pi_{\mathbf{X}_2 | \mathbf{X}_1} \cdots \pi_{\mathbf{X}_d | \mathbf{X}_1, \dots, \mathbf{X}_{d-1}}$$

## Intuitive result

- If  $\eta, p_0$  are  $C^\alpha$ , then so is the KR-map  $S_{\eta, p_0}$  [Santambrogio '15].
- For **smoothness level**  $\alpha > 0$  and  $0 < c < B < \infty$ , let

$$\mathcal{M}(\alpha, B, c) := \left\{ \nu \in C^\alpha([0, 1]^d), \|\nu\|_{C^\alpha} \leq B, \nu \geq c, \int \nu(x) dx = 1 \right\}.$$

- For  $L, c_{min} > 0$ , define the classes

$$\begin{aligned} \mathcal{S}(\alpha, L, c_{min}) := \left\{ S : [0, 1]^d \rightarrow [0, 1]^d \text{ bijective and triangular,} \right. \\ \left. \|S_k\|_{C^\alpha} \leq L, \partial_k S_k \geq c_{min}, 1 \leq k \leq d \right\}. \end{aligned}$$

Theorem (Wang and Marzouk 2022)

Suppose  $p_0 \in \mathcal{M}(\alpha, B, c)$  (and that  $\eta$  is smooth). Then, for some  $L, c_{min} > 0$ , maximizers  $\hat{S}$  over  $\mathcal{S}(\alpha, L, c_{min})$  satisfy

$$E_{P_0}^N[h^2(\hat{S}^\sharp \eta, p_0)] \lesssim N^{-\frac{2(\alpha-1)}{2(\alpha-1)+d}}.$$

# Why?

- The estimator  $\hat{S}^\# \eta$  is equivalently an **MLE**:

$$\hat{S}^\# \eta \in \arg \max_{p \in \mathcal{P}} \sum_{i=1}^N \log p(X_i), \quad \mathcal{P} = \{S^\# \eta : S \in \mathcal{S}\}.$$

## Proof ingredients

- If  $S, \eta \in C^\alpha$ , then  $S^\# \eta \in C^{\alpha-1}$ .
- Hellinger convergence theory for MLEs [e.g. van de Geer 2000]

# Anisotropic smoothness and minimax rates

The previous result is **not** minimax-optimal. Define the anisotropic subclasses

$$\mathcal{AS}(\alpha, L, c_{min}) := \left\{ S \in \mathcal{S}(\alpha, L, c_{min}), \forall 1 \leq k \leq d : \|\partial_k S_k\|_{C^\alpha([0,1]^k)} \leq L \right\}$$

Theorem (Wang and Marzouk 2022)

*The transport map MLE  $\hat{S}$  based on classes  $\mathcal{AS}$  satisfies minimax optimal rates*

$$E_{P_0^N} [h(\hat{S}^\# \eta, p_0)^2] \lesssim N^{-\frac{2\alpha}{2\alpha+d}}.$$

## General penalized estimators

The sets  $\mathcal{AS}(\alpha, L, c_{min})$  may be hard to optimize over. In practice, one may want to re-parameterize transport maps  $S_\theta$  via a (e.g. Euclidean) parameter  $\theta \in \Theta$ .

- ▶ Let  $\Theta$  be a set parameterising triangular maps  
 $\mathcal{S} = \{S_\theta : [0, 1]^d \rightarrow [0, 1]^d, \theta \in \Theta\}$ .
- ▶ Penalized objective

$$\mathcal{J}_{N,\lambda}(\theta) = -\frac{1}{N} \sum_{i=1}^N \log [\eta(S_\theta(X_i)) \det \nabla S_\theta(X_i)] + \lambda^2 \text{pen}(\theta)^2,$$
$$\hat{\theta} \in \arg \min_{\theta \in \Theta} \mathcal{J}_{N,\lambda}(\theta).$$

## General theorem (triangular maps)

Define  $\|S\|_{C_{diag}^1} := \sum_{k=1}^d \|S_k\|_\infty + \|\partial_k S_k\|_\infty$ . For any  $\theta^* \in \Theta$ , let

$$\mathcal{S}(\lambda, R) := \{S_\theta : h^2(S_\theta^\# \eta, S_{\theta^*}^\# \eta) + \lambda^2 \text{pen}(\theta)^2 \leq R^2\},$$

$$\mathcal{J}(\lambda, R) := R + \int_0^R H^{1/2}(\mathcal{S}(\lambda, R), \|\cdot\|_{C_{diag}^1}, \rho) d\rho.$$

Theorem (Wang and Marzouk 2022)

Suppose that  $K^{-1} \leq p_0, \eta \leq K$ , and that  $\{S_\theta : \theta \in \Theta\}$  is uniformly bounded in  $C_{diag}^1$ . Then there exist  $C, \gamma > 0$  such that for any  $\lambda, \delta > 0$  satisfying

$$\delta^2 \geq \frac{C\mathcal{J}(\lambda, \delta)}{\sqrt{N}}, \quad \text{we have that}$$

$$\mathbb{E}_0^N [h^2(S_{\hat{\theta}}^\# \eta, p_0)] \lesssim h^2(S_{\theta^*}^\# \eta, p_0) + \lambda^2 \text{pen}(\theta^*)^2 + \delta^2.$$

# Parameterisation of Knothe-Rosenblatt maps

Let  $U = V = [0, 1]^d$ . Three required properties:

- ▶ Triangularity
- ▶ Monotonicity
- ▶ Range constraint

Example: Rational parameterization

For  $x \in [0, 1]^d$  and  $1 \leq k \leq d$ , let

$$S_{F,k}(x) := \frac{\int_0^{x_k} \Phi(F_k(x_{1:k-1}, y)) dy}{\int_0^1 \Phi(F_k(x_{1:k-1}, y)) dy}, \quad x_{1:k} \in [0, 1]^d.$$

- ▶  $\Phi : \mathbb{R} \rightarrow (K_{min}, K_{max})$  is a 'link function'
- ▶  $F : [0, 1]^d \rightarrow \mathbb{R}^d$  is any (say,  $L^\infty$ ) function.

- ▶ Natural parameterizations of triangular maps with  $H^\alpha$  Sobolev penalty, or with high-dimensional wavelet penalty, achieve the minimax rate.
- ▶ The general theorem also holds for general non-triangular classes of maps, and on general bounded domains.

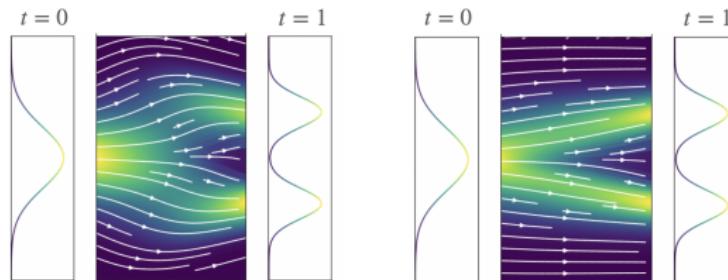
## ODE couplings of probability distributions

Let  $D = [0, 1]^d$ , and  $\Omega = D \times [0, 1]$ . Let  $f : \Omega \mapsto \mathbb{R}^d$  be a *velocity field* which governs the ODE

$$\begin{cases} \frac{d}{dt} u(t) = f(u(t), t), & t \in (0, 1), \\ u(0) = x. \end{cases}$$

This defines unique trajectories (flow)

$$X_f(x, t) = x + \int_0^t f(X_f(x, s), s) ds, \quad t \in [0, 1], \quad x \in D.$$



Neural network parameterization of  $f \in \mathcal{F} \equiv$  neural ODEs.

# Parameterization of velocity fields

Minimal requirement:

$$\mathcal{V} = \left\{ f : \Omega \rightarrow \mathbb{R}^d \mid f \in C^1(\Omega), f \cdot \nu \equiv 0 \text{ on } \partial D \times [0, 1] \right\}.$$

## Lemma

If  $f \in \mathcal{V}$ , then  $X_f(\cdot, t) : D \rightarrow D$  is a diffeomorphism for any  $t \in [0, 1]$ , and the pullback density is given by

$$(X_f(\cdot, t))^{\#} \rho(x) = \rho(X_f(x, t)) \det [\nabla_x X_f(x, t)].$$

- ▶  $\mathcal{F} \subseteq \mathcal{V}$  class of velocity fields
- ▶ Let  $T^f = X_f(\cdot, 1)$  (time-one flow map)

## Training objective

$$\hat{f}_{\text{ODE}} := \arg \max_{f \in \mathcal{F}} \sum_{i \in [n]} \log \rho(T^f(X_i)) \det [\nabla_x T^f(X_i)].$$

## General convergence theorem

- ▶ Suppose  $(X_i : 1 \leq i \leq n) \sim^{i.i.d.} p_0 \leq K$ .
- ▶  $\rho \equiv 1$  uniform reference on  $D = (0, 1)^d$ .
- ▶ For some constant  $B > 0$ ,

$$\sup_{f \in \mathcal{F}} \left( \|f\|_{C^1(\Omega)} + \sup_{t \in [0, 1]} \|\nabla_x f(\cdot, t)\|_{Lip} \right) \leq B, \quad (1)$$

- ▶ Define  **$C^1$ -metric entropy** integral

$$I(\mathcal{F}, R) := R + \int_0^R \sqrt{\log N(\mathcal{F}, \|\cdot\|_{C^1}, \rho)} d\rho.$$

Theorem (Marzouk, Ren, W, Zech 2023)

There exists  $C > 0$  such that for all  $f^* \in \mathcal{F}$  and all  $\delta_N > 0$  with

$$\sqrt{N} \delta_N^2 \geq C \cdot I(\mathcal{F}, \delta_N), \quad (2)$$

$$\mathbb{E}_{p_0}^N [h((T^{\hat{f}})^\# \rho, p_0)] \lesssim \underbrace{h((T^{f^*})^\# \rho, p_0)}_{\text{approximation term}} + \delta_N. \quad (3)$$

## Proof idea

### Lemma (Local Lipschitz parameterisation)

We have the local Lipschitz estimates (on  $W^{2,\infty}$ -bounded sets)

$$\|(\mathcal{T}^f)^\# \rho - (\mathcal{T}^g)^\# \rho\|_{C(D)} \lesssim \|\mathcal{T}^f - \mathcal{T}^g\|_{C^1(D)} \lesssim \|f - g\|_{C^1(\Omega)}.$$

### Lemma (Bounds for induced transport maps)

Suppose that  $\sup_{f \in \mathcal{F}} \|f\|_{C^1(\Omega)} =: M < \infty$ . Then, for all  $f \in \mathcal{F}$ , we have

$$\sup_{x \in D} \|\nabla(\mathcal{T}^f)(x)\|_{\mathbb{R}^d \rightarrow \mathbb{R}^d} \leq 1 + dM e^{dM}.$$

The largest and smallest eigenvalues of  $\nabla(\mathcal{T}^f(x))$  are bounded as

$$\sup_{f \in \mathcal{F}} \sup_{x \in D} \lambda_{\max}^f(x) \leq 1 + dM e^{dM}, \quad \inf_{f \in \mathcal{F}} \inf_{x \in D} \lambda_{\min}^f(x) \geq (1 + dM e^{dM})^{-1}.$$

## Regularity theorem

Lemma (Existence of  $C^k$  coupling velocity field)

Let  $p_0 \in C^k([0, 1]^d)$ . Then, there exists some  $f_{p_0}^\Delta$  such that  $(T^{f_{p_0}^\Delta})^\# \rho = p_0$ , and such that  $f_{p_0}^\Delta \in C^k(\Omega)$ . Moreover, the velocity field  $g$  with components

$$[g(x, s)]_j := \frac{(f_{p_0}^\Delta(x, s))_j}{x_j(1 - x_j)}, \quad j = 1, \dots, d, \tag{4}$$

also belongs to  $C^k(\Omega)$ . Consequently,  $f_{p_0}^\Delta \in \mathcal{V} \cap C^k(\Omega)$ .

## Construction of $C^k$ vector field

Let  $T$  be the KR-map pushing  $p_0$  to  $\rho$ , and let

$$G_t(x) = tT(x) + (1-t)x$$

be the straight-line interpolation. Then let  $F : D \times [0, 1] \rightarrow D$ ,  $F(x, t) = G_t^{-1}(x)$ , and define

$$f_{p_0}^\Delta(y, s) = T(F(y, s)) - F(y, s).$$

- ▶ This vector field satisfies the desired regularity.

## $C^1$ -covering of $C^k$ -spaces

For  $0 < s_1, s_2 < \infty$ ,  $R > 0$ ,  $\tau > 0$ ,

$$H(\{f : \|f\|_{B_{\infty\infty}^{s_1}} \leq R\}, B_{\infty\infty}^{s_2}(\Omega), \tau) \leq C(R/\tau)^{\frac{d}{s_1-s_2}}.$$

# Convergence rate for $C^k$ -classes

Define the  $C^k$  classes

$$\mathcal{F}(B) := \left\{ f \in C^k(\Omega, \mathbb{R}^d) : \|f\|_{C^k} \leq B, \right. \\ \left. f(x, t) \cdot \nu_x \equiv 0 \text{ for all } (t, x) \in [0, 1] \times \partial D \right\},$$

## Theorem

Let  $p_0 \in C^k$  and  $\mathcal{F} = \mathcal{F}(B)$ . Then, it holds that for all  $n \geq 1$ ,

$$\mathbb{E}_{p_0}^N [h^2((T^{\hat{f}})^{\#} \rho, p_0)] \lesssim N^{-\eta}, \quad \text{with } \eta = \frac{2(k-1-\gamma)}{2(k-1-\gamma)+d+1} > 0.$$

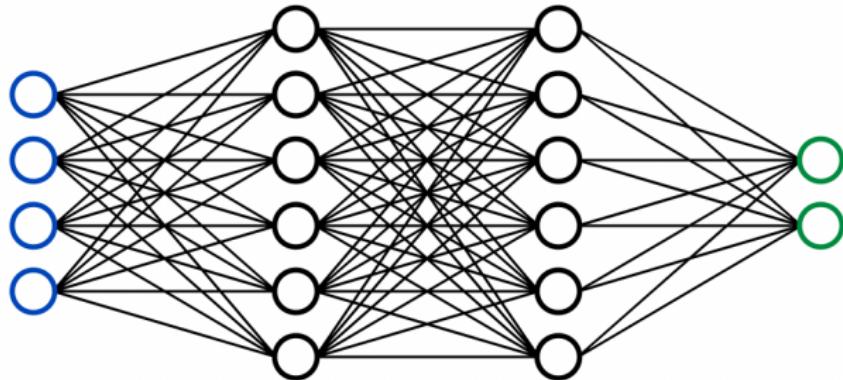
- Approximation of  $\mathcal{F}(B)$  by wavelets, polynomials, trig. polynomials possible

## Neural network classes

- ▶ Suppose  $p_0 \in \mathcal{M}(k, L_1, L_2)$  is  $C^k(D)$ .
- ▶ Let

$$\begin{aligned}\mathcal{F}_{\text{NN}}(L, W, S, B, R) &= \Phi_{\text{NN}}^{d+1, d}(L, W, S, B) \\ &\cap \{f \in W^{2,\infty}(\Omega) : \|f\|_{W^{2,\infty}(\Omega)} \leq R\},\end{aligned}$$

be the network class with ReLU<sup>2</sup> activation function, mapping from  $\Omega$  to  $\mathbb{R}^d$ .



# Theorem for neuralODE

Set

- ▶  $L = O(1)$  (depth)
- ▶  $W = O(N^{\frac{d+1}{d+1+2(k-1)}})$  (width),
- ▶  $S = O(N^{\frac{d+1}{d+1+2(k-1)}})$  (sparsity),
- ▶  $B = O(N^{\frac{d+1}{d+1+2(k-1)}})$  ( $\ell^\infty$  bound on weights)
- ▶  $R = O(1)$  (large enough).

## Theorem

The neuralODE estimator over  $\mathcal{F}_{NN}(L, W, S, B, R)$  satisfies

$$\mathbb{E}_{P_0}^N [h^2((T^{\hat{f}_{ODE}})^\sharp \rho, p_0)] \lesssim N^{-\frac{2(k-1)}{2(k-1)+d+1}} \log N.$$

### Theorem

Consider the  $\text{ReLU}^2$  network space  $\Phi(L, W, S, B)$  of networks  $\mathbb{R}^d \rightarrow \mathbb{R}$  with  $L = \mathcal{O}(1)$ ,  $W = \mathcal{O}(M)$ ,  $S = \mathcal{O}(M)$  and  $B = \mathcal{O}(M)$ . Then

$$H(\Phi(L, W, S, B), C^1([0, 1]^d), \tau) = \mathcal{O}(M \log(\tau^{-1}) + M \log M).$$

- ▶ Builds on existing bounds from Schmidt-Hieber (2020), Suzuki (2019) from the regression setting.
- ▶ Modifications of previous results to  $\text{ReLU}^2$  activation functions.

## Proof ingredients II: approximation

### Theorem

Let  $d, k, m \geq 1$  and  $m \geq k + 1$ . Then there exists  $C = C(d, k, m)$  such that for all  $f \in C^k([0, 1]^d, \mathbb{R})$  and all  $M \in \mathbb{N}$  there exists a ReLU $^{m-1}$  neural network  $\tilde{f} \in \Phi(L, W, S, B)$  mapping from  $\mathbb{R}^d$  to  $\mathbb{R}$  with

$$L \leq C, \quad W \leq M, \quad S \leq M, \quad B \leq C\|f\| + M^{1/d} \quad (5)$$

such that  $\tilde{f} \in C^{m-2}([0, 1]^d, \mathbb{R})$  and

$$\|f - \tilde{f}\|_{W^{r,\infty}([0,1]^d)} \leq CM^{-\frac{k-r}{d}} \|f\|_{C^k([0,1]^d)} \quad \forall r \in \{0, \dots, k\}. \quad (6)$$

- ▶ Adapts classical neural network approximation results (e.g. Pinkus 1999, Yarotsky 2017) to the setting with smoother activation functions.

- ▶ **Brenier maps** are known to possess regularity properties
  - ▶ Statistical convergence rates?
  - ▶ How to parameterize Brenier maps?
- ▶ Extension to **high dimensions**
- ▶ Theoretical guarantees for **conditional sampling**
- ▶ Flow matching methods

## References

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**Thank you!**